

MinAndMax(A, n)

$_{1} \ large = \max(A[1], A[2])$	
small = min(A[1], A[2])	
3 for $i = 2$ to $\lfloor n/2 \rfloor$ do	
$ a large = \max(large, \max(A[2i-1], A[2i])) $	
s $small = min(small, min(A[2i - 1], A[2i]))$	
6 end	
7 if n is odd then	
$ large = \max(large, A[n])$	
$small = \min(small, A[n])$	
10 return (large, small)	

Explanation of MinAndMax

- Idea: For each pair of values examined in the loop, compare them directly
- ▶ For each such pair, compare the smaller one to *small* and the larger one to large
- ► Example: *A* = [8, 5, 3, 10, 4, 12, 6]

Efficiency of MinAndMax

- How many comparisons does MinAndMax make?
- Initialization on Lines 1 and 2 requires only one comparison
- Each iteration through the loop requires one comparison between A[2i-1] and A[2i] and then one comparison to each of large and small, for a total of three
- Lines 8 and 9 require one comparison each
- ▶ Total is at most $1 + 3(\lfloor n/2 \rfloor 1) + 2 \le 3\lfloor n/2 \rfloor$, which is better than 2n - 3 for finding minimum and maximum separately

Selection of the *i*th Smallest Value

- ▶ Now to the general problem: Given A and i, return the ith smallest value in A
- Obvious solution is sort and return *i*th element
- Time complexity is $\Theta(n \log n)$
- Can we do better?

10, 10, 10, 12, 12, 12, 20, 00, 00

Selection of the *i*th Smallest Value (2)

- New algorithm: Divide and conquer strategy
- Idea: Somehow discard a constant fraction of the current array after spending only linear time
 - If we do that, we'll get a better time complexity
 - More on this later
- Which fraction do we discard?

Select(A, p, r, i)

- 3 q = Partition(A, p, r) // Like Partition in Quicksort

- 4 k = q p + 1 // Size of $A[p \cdots q]$ 5 if i = k then 6 return A[q] // Pivot value is the answer 7 else if i < k then
- return Select(A, p, q 1, i) // Answer is in left subarray
- 9 els
- 10 return Select(A, q + 1, r, i - k) // Answer is in right subarray 11

Returns *i*th smallest element from $A[p \cdots r]$

What is Select Doing?

- Like in Quicksort, Select first calls Partition, which chooses a pivot element q, then reorders A to put all elements < A[q] to the left of A[q] and all elements > A[q] to the right of A[q]
- ▶ E.g. if A = [1, 7, 5, 4, 2, 8, 6, 3] and pivot element is 5, then result is A' = [1, 4, 2, 3, 5, 7, 8, 6]
- If A[q] is the element we seek, then return it
- If sought element is in left subarray, then recursively search it, and ignore right subarray
- If sought element is in right subarray, then recursively search it, and ignore left subarray

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Partition(A, p, r)

 $\begin{array}{c|c} 1 & x = \text{ChoosePivotElement}(A, p, r) \ // \ \text{Returns index of pivot} \\ 2 & \text{exchange } A[x] \ \text{with } A[r] \\ 3 & i = p - 1 \\ 4 & \text{for } j = p \ \text{to } r - 1 \ \text{do} \\ 5 & | & \text{if } A[i] \leq A[r] \ \text{then} \\ 6 & | & i = i + 1 \\ 7 & | & \text{exchange } A[i] \ \text{with } A[j] \\ 8 & | \\ 9 & \text{end} \\ 10 & \text{exchange } A[i + 1] \ \text{with } A[r] \end{array}$

11 return i + 1

Chooses a pivot element and partitions $A[p\cdots r]$ around it

Partitioning the Array: Example (Fig 7.1)

$ \begin{array}{c} i & j' \\ 2 & 8 & 7 & 1 & 3 & 5 & 6 \\ p^{j} & j \\ 2 & 8 & 7 & 1 & 3 & 5 & 6 \\ \hline p^{j} & j \\ 2 & 8 & 7 & 1 & 3 & 5 & 6 \\ \hline p^{j} & j \\ 2 & 1 & 7 & 1 & 3 & 5 & 6 \\ \hline p^{j} & j \\ 2 & 1 & 7 & 8 & 5 & 5 & 6 \\ \hline p^{j} & 1 & 3 & 5 & 6 & 4 \\ \hline p^{j} & 1 & 3 & 5 & 6 & 4 \\ \hline p^{j} & 1 & 3 & 8 & 5 & 5 & 6 \\ \hline p^{j} & 1 & 3 & 8 & 7 & 8 & 6 \\ \hline p^{j} & 1 & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 \\ \hline p^{j} & 1 & 1 \\ \hline p^{j} & 1 & 1 & 1 \\ \hline p^{j} &$
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Choosing a Pivot Element

Choice of pivot element is critical to low time complexity

- Why?
- What is the best choice of pivot element to partition $A[p \cdots r]$?

Choosing a Pivot Element (2)

- Want to pivot on an element that it as close as possible to being the median
- Of course, we don't know what that is
- > Will do median of medians approach to select pivot element

Median of Medians

- ▶ Given (sub)array A of n elements, partition A into m = ⌊n/5⌋ groups of 5 elements each, and at most one other group with the remaining n mod 5 elements
- ▶ Make an array A' = [x₁, x₂,..., x_[n/5]], where x_i is median of group i, found by sorting (in constant time) group i
- ▶ Call Select(A', 1, $\lceil n/5 \rceil$, $\lfloor (\lceil n/5 \rceil + 1)/2 \rfloor$) and use the returned element as the pivot

Example

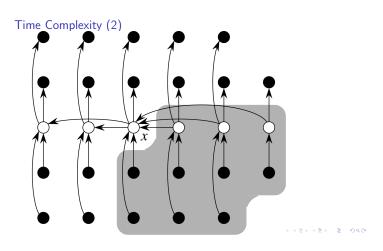
Split into teams, and work this example on the board: Find the 4th smallest element of A = [4, 9, 12, 17, 6, 5, 21, 14, 8, 11, 13, 29, 3]Show results for each step of Select, Partition, and ChoosePivotElement

Time Complexity

- ► Key to time complexity analysis is lower bounding the fraction of elements discarded at each recursive call to Select
- On next slide, medians and median (x) of medians are marked, arrows indicate what is guaranteed to be greater than what
- Since x is less than at least half of the other medians (ignoring group with < 5 elements and x's group) and each of those medians is less than 2 elements, we get that the number of elements x is less than is at least

$$3\left(\left\lceil\frac{1}{2}\left\lceil\frac{n}{5}\right\rceil\right\rceil-2\right)\geq\frac{3n}{10}-6\geq n/4\qquad\text{(if }n\geq120\text{)}$$

- \blacktriangleright Similar argument shows that at least $3n/10-6 \geq n/4$ elements are less than x
- \blacktriangleright Thus, if $n \ge 120$, each recursive call to Select is on at most 3n/4 elements

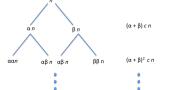


Time Complexity (3)

- ► Now can develop a recurrence describing Select's time complexity
- Let T(n) represent total time for Select to run on input of size n
- Choosing a pivot element takes time O(n) to split into size-5 groups and time T(n/5) to recursively find the median of medians
- Once pivot element chosen, partitioning n elements takes O(n) time
- Recursive call to Select takes time at most T(3n/4)
- Thus we get
 - $T(n) \leq T(n/5) + T(3n/4) + O(n)$
- Can express as $T(\alpha n) + T(\beta n) + O(n)$ for $\alpha = 1/5$ and $\beta = 3/4$
- ▶ **Theorem:** For recurrences of the form $T(\alpha n) + T(\beta n) + O(n)$ for $\alpha + \beta < 1$, T(n) = O(n)
- Thus Select has time complexity O(n)

Proof of Theorem

Top T(n) takes O(n) time (= cn for some constant c). Then calls to $T(\alpha n)$ and $T(\beta n)$, which take a total of $(\alpha + \beta)cn$ time, and so on.



Summing these infinitely yields (since $\alpha + \beta < 1$)

$$cn(1+(\alpha+\beta)+(\alpha+\beta)^2+\cdots)=\frac{cn}{1-(\alpha+\beta)}=c'n=O(n)$$

Master Method

- Another useful tool for analyzing recurrences
- Theorem: Let a ≥ 1 and b > 1 be constants, let f(n) be a function, and let T(n) be defined as T(n) = aT(n/b) + f(n). Then T(n) is bounded as follows.
 - 1. If $f(n) = O(n^{\log_b a \epsilon})$ for constant $\epsilon > 0$, then $T(n) = \Theta(n^{\log_b a})$
 - 2. If $f(n) = \Theta(n^{\log_2 a})$, then $T(n) = \Theta(n^{\log_2 a} \log n)$ 3. If $f(n) = \Omega(n^{\log_2 a})$, then $T(n) = \Theta(n^{\log_2 a} \log n)$ 5. If $f(n) = \Omega(n^{\log_2 a+\epsilon})$ for constant $\epsilon > 0$, and if $af(n/b) \le cf(n)$ for
 - 3. If $f(n) = \Omega(n^{\omega_{b,b}(r)})$ for constant $\epsilon > 0$, and if $af(n/b) \le cf(n)$ for constant c < 1 and sufficiently large n, then $T(n) = \Theta(f(n))$
- ► E.g. for Select, can apply theorem on T(n) < 2T(3n/4) + O(n) (note the slack introduced) with a = 2, b = 4/3, ε = 1.4 and get T(n) = O(n^{log_{4/3}2}) = O(n^{2.41})
- \Rightarrow Not as tight for this recurrence