

Computer Science & Engineering 423/823

Design and Analysis of Algorithms

Lecture 08 — All-Pairs Shortest Paths (Chapter 25)

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Introduction

- ▶ Similar to SSSP, but find shortest paths for *all pairs* of vertices
- ▶ Given a weighted, directed graph $G = (V, E)$ with weight function $w : E \rightarrow \mathbb{R}$, find $\delta(u, v)$ for all $(u, v) \in V \times V$
- ▶ One solution: Run an algorithm for SSSP $|V|$ times, treating each vertex in V as a source
 - ▶ If no negative weight edges, use Dijkstra's algorithm, for time complexity of $O(|V|^3 + |V||E|) = O(|V|^3)$ for array implementation, $O(|V||E| \log |V|)$ if heap used
 - ▶ If negative weight edges, use Bellman-Ford and get $O(|V|^2|E|)$ time algorithm, which is $O(|V|^4)$ if graph dense
- ▶ Can we do better?
 - ▶ Matrix multiplication-style algorithm: $\Theta(|V|^3 \log |V|)$
 - ▶ Floyd-Warshall algorithm: $\Theta(|V|^3)$
 - ▶ Both algorithms handle negative weight edges

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Adjacency Matrix Representation

- ▶ Will use adjacency matrix representation
- ▶ Assume vertices are numbered: $V = \{1, 2, \dots, n\}$
- ▶ Input to our algorithms will be $n \times n$ matrix W :

$$w_{ij} = \begin{cases} 0 & \text{if } i = j \\ \text{weight of edge } (i, j) & \text{if } (i, j) \in E \\ \infty & \text{if } (i, j) \notin E \end{cases}$$

- ▶ For now, assume negative weight cycles are absent
- ▶ In addition to distance matrices L and D produced by algorithms, can also build *predecessor matrix* Π , where π_{ij} = predecessor of j on a shortest path from i to j , or NIL if $i = j$ or no path exists
 - ▶ Well-defined due to optimal substructure property

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Print-All-Pairs-Shortest-Path(Π, i, j)

```

1 if i == j then
2   | print i ;
3 else if  $\pi_{ij}$  == NIL then
4   | print "no path from " i " to " j " exists" ;
5 else
6   | PRINT-ALL-PAIRS-SHORTEST-PATH( $\Pi, i, \pi_{ij}$ ) ;
7   | print j ;

```

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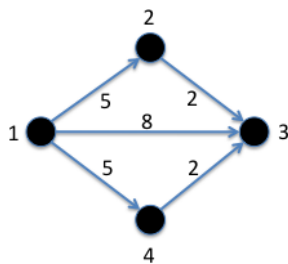
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Notes and Questions

Notes and Questions

Shortest Paths and Matrix Multiplication

- Will maintain a series of matrices $L^{(m)} = (\ell_{ij}^{(m)})$, where $\ell_{ij}^{(m)}$ = the minimum weight of any path from i to j that uses at most m edges
 - Special case: $\ell_{ij}^{(0)} = 0$ if $i = j$, ∞ otherwise



$$\ell_{13}^{(0)} = \infty, \ell_{13}^{(1)} = 8, \ell_{13}^{(2)} = 7$$

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Notes and Questions

Recursive Solution

- Exploit optimal substructure property to get a recursive definition of $\ell_{ij}^{(m)}$
- To follow shortest path from i to j using at most m edges, either:
 - Take shortest path from i to j using $\leq m-1$ edges and stay put, or
 - Take shortest path from i to some k using $\leq m-1$ edges and traverse edge (k, j)

$$\ell_{ij}^{(m)} = \min \left(\ell_{ij}^{(m-1)}, \min_{1 \leq k \leq n} (\ell_{ik}^{(m-1)} + w_{kj}) \right)$$

- Since $w_{jj} = 0$ for all j , simplify to

$$\ell_{ij}^{(m)} = \min_{1 \leq k \leq n} (\ell_{ik}^{(m-1)} + w_{kj})$$

- If no negative weight cycles, then since all shortest paths have $\leq n-1$ edges,

$$\delta(i, j) = \ell_{ij}^{(n-1)} = \ell_{ij}^{(n)} = \ell_{ij}^{(n+1)} = \dots$$

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Notes and Questions

Bottom-Up Computation of L Matrices

- Start with weight matrix W and compute series of matrices $L^{(1)}, L^{(2)}, \dots, L^{(n-1)}$
- Core of the algorithm is a routine to compute $L^{(m+1)}$ given $L^{(m)}$ and W
- Start with $L^{(1)} = W$, and iteratively compute new L matrices until we get $L^{(n-1)}$
 - Why is $L^{(1)} = W$?
- Can we detect negative-weight cycles with this algorithm? How?

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Notes and Questions

Navigation icons: back, forward, search, etc.

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Extend-Shortest-Paths(L, W)

Notes and Questions

```

1  $n$  = number of rows of  $L$  // This is  $L^{(m)}$  ;
2 create new  $n \times n$  matrix  $L'$  // This will be  $L^{(m+1)}$  ;
3 for  $i = 1$  to  $n$  do
4   for  $j = 1$  to  $n$  do
5      $\ell'_{ij} = \infty$  ;
6     for  $k = 1$  to  $n$  do
7        $\ell'_{ij} = \min(\ell'_{ij}, \ell_{ik} + w_{kj})$ 
8     end
9   end
10 end
11 return  $L'$  ;

```

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Slow-All-Pairs-Shortest-Paths(W)

Notes and Questions

```

1  $n$  = number of rows of  $W$  ;
2  $L^{(1)} = W$  ;
3 for  $m = 2$  to  $n - 1$  do
4    $L^{(m)} = \text{EXTEND-SHORTEST-PATHS}(L^{(m-1)}, W)$  ;
5 end
6 return  $L^{(n-1)}$  ;

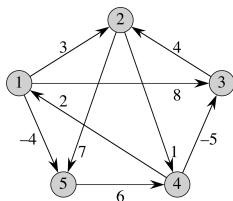
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Example

Notes and Questions



$$L^{(1)} = \begin{pmatrix} 0 & 3 & 8 & \infty & -4 \\ \infty & 0 & \infty & 1 & 7 \\ \infty & 4 & 0 & \infty & \infty \\ 2 & \infty & -5 & 0 & \infty \\ \infty & \infty & \infty & 6 & 0 \end{pmatrix} \quad L^{(2)} = \begin{pmatrix} 0 & 3 & 8 & 2 & -4 \\ 3 & 0 & -4 & 1 & 7 \\ \infty & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & \infty & 1 & 6 & 0 \end{pmatrix}$$

$$L^{(3)} = \begin{pmatrix} 0 & 3 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 11 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix} \quad L^{(4)} = \begin{pmatrix} 0 & 1 & -3 & 2 & -4 \\ 3 & 0 & -4 & 1 & -1 \\ 7 & 4 & 0 & 5 & 3 \\ 2 & -1 & -5 & 0 & -2 \\ 8 & 5 & 1 & 6 & 0 \end{pmatrix}$$

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Improving Running Time

Notes and Questions

- ▶ What is time complexity of SLOW-ALL-PAIRS-SHORTEST-PATHS?
- ▶ Can we do better?
- ▶ Note that if, in EXTEND-SHORTEST-PATHS, we change $+$ to \min , multiplication and \min to $+$, get matrix multiplication of L and W
- ▶ If we let \odot represent this “multiplication” operator, then SLOW-ALL-PAIRS-SHORTEST-PATHS computes

$$\begin{aligned} L^{(2)} &= L^{(1)} \odot W = W^{(2)}, \\ L^{(3)} &= L^{(2)} \odot W = W^{(3)}, \\ &\vdots \\ L^{(n-1)} &= L^{(n-2)} \odot W = W^{n-1} \end{aligned}$$

- ▶ Thus, we get $L^{(n-1)}$ by iteratively “multiplying” W via **EXTEND-SHORTEST-PATHS**

Improving Running Time (2)

Notes and Questions

- ▶ But we don't need every $L^{(m)}$; we only want $L^{(n-1)}$
- ▶ E.g., if we want to compute 7^{64} , we could multiply 7 by itself 64 times, or we could square it 6 times
- ▶ In our application, once we have a handle on $L^{((n-1)/2)}$, we can immediately get $L^{(n-1)}$ from one call to $\text{EXTEND-SHORTEST-PATHS}(L^{((n-1)/2}), L^{((n-1)/2})$
- ▶ Of course, we can similarly get $L^{((n-1)/2)}$ from "squaring" $L^{((n-1)/4)}$, and so on
- ▶ Starting from the beginning, we initialize $L^{(1)} = W$, then compute $L^{(2)} = L^{(1)} \odot L^{(1)}$, $L^{(4)} = L^{(2)} \odot L^{(2)}$, $L^{(8)} = L^{(4)} \odot L^{(4)}$, and so on
- ▶ What happens if $n - 1$ is not a power of 2 and we "overshoot" it?
- ▶ How many steps of repeated squaring do we need to make?
- ▶ What is time complexity of this new algorithm?

Faster-All-Pairs-Shortest-Paths(W)

Notes and Questions

```

1  $n$  = number of rows of  $W$  ;
2  $L^{(1)} = W$  ;
3  $m = 1$  ;
4 while  $m < n - 1$  do
5   |  $L^{(2m)} = \text{EXTEND-SHORTEST-PATHS}(L^{(m)}, L^{(m)})$  ;
6   |  $m = 2m$  ;
7 end
8 return  $L^{(m)}$  ;

```

- ▶ Shaves the logarithmic factor off of the previous algorithm
- ▶ As with previous algorithm, start by assuming that there are no negative weight cycles; can detect negative weight cycles the same way as before
- ▶ Considers a different way to decompose shortest paths, based on the notion of an *intermediate vertex*
 - ▶ If simple path $p = \langle v_1, v_2, v_3, \dots, v_{\ell-1}, v_\ell \rangle$, then the set of intermediate vertices is $\{v_2, v_3, \dots, v_{\ell-1}\}$

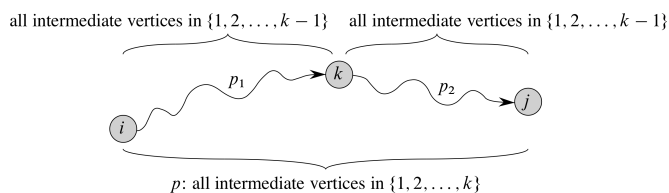
Structure of Shortest Path

Notes and Questions

- ▶ Again, let $V = \{1, \dots, n\}$, and fix $i, j \in V$
- ▶ For some $1 \leq k \leq n$, consider set of vertices $V_k = \{1, \dots, k\}$
- ▶ Now consider all paths from i to j whose intermediate vertices come from V_k and let p be a minimum-weight path from them
- ▶ Is $k \in p$?
 1. If not, then all intermediate vertices of p are in V_{k-1} , and a SP from i to j based on V_{k-1} is also a SP from i to j based on V_k
 2. If so, then we can decompose p into $i \xrightarrow{p_1} k \xrightarrow{p_2} j$, where p_1 and p_2 are each shortest paths based on V_{k-1}

Structure of Shortest Path (2)

Notes and Questions



Recursive Solution

Notes and Questions

- ▶ What does this mean?
- ▶ It means that a shortest path from i to j based on V_k is either going to be the same as that based on V_{k-1} , or it is going to go through k
- ▶ In the latter case, a shortest path from i to j based on V_k is going to be a shortest path from i to k based on V_{k-1} , followed by a shortest path from k to j based on V_{k-1}
- ▶ Let matrix $D^{(k)} = \left(d_{ij}^{(k)}\right)$, where $d_{ij}^{(k)}$ = weight of a shortest path from i to j based on V_k :

$$d_{ij}^{(k)} = \begin{cases} w_{ij} & \text{if } k = 0 \\ \min(d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}) & \text{if } k \geq 1 \end{cases}$$

- ▶ Since all SPs are based on $V_n = V$, we get $d_{ij}^{(n)} = \delta(i, j)$ for all $i, j \in V$

Floyd-Warshall(W)

Notes and Questions

```

1  $n$  = number of rows of  $W$  ;
2  $D^{(0)} = W$  ;
3 for  $k = 1$  to  $n$  do
4     for  $i = 1$  to  $n$  do
5         for  $j = 1$  to  $n$  do
6              $d_{ij}^{(k)} = \min \left( d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)} \right)$ 
7         end
8     end
9 end
10 return  $D^{(n)}$  ;

```

Transitive Closure

Notes and Questions

- ▶ Used to determine whether paths exist between pairs of vertices
- ▶ Given directed, unweighted graph $G = (V, E)$ where $V = \{1, \dots, n\}$, the *transitive closure* of G is $G^* = (V, E^*)$, where

$$E^* = \{(i, j) : \text{there is a path from } i \text{ to } j \text{ in } G\}$$

- ▶ How can we directly apply Floyd-Warshall to find E^* ?
- ▶ Simpler way: Define matrix T similarly to D :

$$t_{ij}^{(0)} = \begin{cases} 0 & \text{if } i \neq j \text{ and } (i, j) \notin E \\ 1 & \text{if } i = j \text{ or } (i, j) \in E \end{cases}$$

$$t_{ij}^{(k)} = t_{ij}^{(k-1)} \vee \left(t_{ik}^{(k-1)} \wedge t_{kj}^{(k-1)} \right)$$

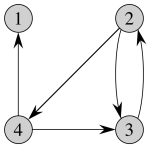
- ▶ I.e., you can reach j from i using V_k if you can do so using V_{k-1} or if you can reach k from i and reach j from k , both using V_{k-1}

```

1 allocate and initialize  $n \times n$  matrix  $T^{(0)}$ ;
2 for  $k = 1$  to  $n$  do
3     allocate  $n \times n$  matrix  $T^{(k)}$ ;
4     for  $i = 1$  to  $n$  do
5         for  $j = 1$  to  $n$  do
6              $t_{ij}^{(k)} = t_{ij}^{(k-1)} \vee t_{ik}^{(k-1)} \wedge t_{kj}^{(k-1)}$ 
7         end
8     end
9 end
10 return  $T^{(n)}$ ;

```

Example



$$T^{(0)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix} \quad T^{(1)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix} \quad T^{(2)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 \end{pmatrix}$$

$$T^{(3)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix} \quad T^{(4)} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix}$$

Notes and Questions

Analysis

- ▶ Like Floyd-Warshall, time complexity is officially $\Theta(n^3)$
- ▶ However, use of 0s and 1s exclusively allows implementations to use bitwise operations to speed things up significantly, processing bits in batch, a word at a time
- ▶ Also saves space
- ▶ Another space saver: Can update the T matrix (and F -W's D matrix) in place rather than allocating a new matrix for each step (Exercise 25.2-4)

Notes and Questions