#### Introduction

#### Computer Science & Engineering 423/823 Design and Analysis of Algorithms

Lecture 02 — Elementary Graph Algorithms (Chapter 22)

Stephen Scott (Adapted from Vinodchandran N. Variyam) Graphs are abstract data types that are applicable to numerous problems
Can capture *entities*, *relationships* between them, the *degree* of the relationship, etc.

- This chapter covers basics in graph theory, including representation, and algorithms for basic graph-theoretic problems (some content was covered in review lecture)
- We'll build on these later this semester

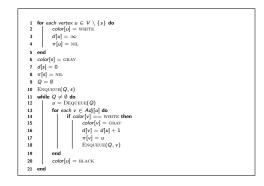
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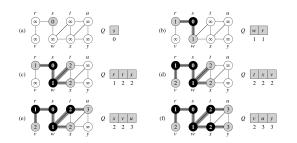
#### Breadth-First Search (BFS)

- Given a graph G = (V, E) (directed or undirected) and a *source* node  $s \in V$ , BFS systematically visits every vertex that is reachable from s
- Uses a queue data structure to search in a breadth-first manner
- ► Creates a structure called a BFS tree such that for each vertex v ∈ V, the distance (number of edges) from s to v in tree is a shortest path in G
- Initialize each node's color to WHITE
- $\blacktriangleright$  As a node is visited, color it to  $_{\rm GRAY}$  ( $\Rightarrow$  in queue), then  $_{\rm BLACK}$  ( $\Rightarrow$  finished)

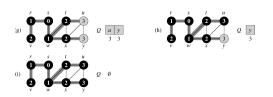
## BFS(*G*, *s*)



#### **BFS** Example



#### BFS Example (2)



#### **BFS** Properties

#### Depth-First Search (DFS)

- What is the running time?
  - Hint: How many times will a node be enqueued?
- After the end of the algorithm, d[v] = shortest distance from s to v ⇒ Solves unweighted shortest paths
  - Can print the path from s to v by recursively following  $\pi[v]$ ,  $\pi[\pi[v]]$ , etc.

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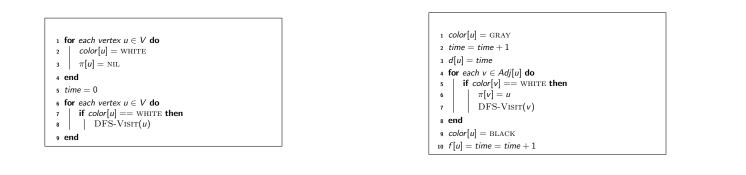
- If  $d[v] == \infty$ , then v not reachable from s
  - $\Rightarrow$  Solves reachability

Another graph traversal algorithm

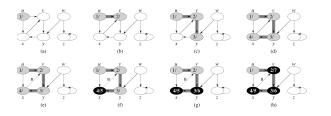
- Unlike BFS, this one follows a path as deep as possible before backtracking
- ▶ Where BFS is "queue-like," DFS is "stack-like"
- Tracks both "discovery time" and "finishing time" of each node, which will come in handy later

DFS(G)

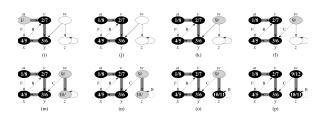
## $\mathsf{DFS-Visit}(u)$



# DFS Example



#### DFS Example (2)



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#### **DFS** Properties

#### • Time complexity same as BFS: $\Theta(|V| + |E|)$

- Vertex u is a proper descendant of vertex v in the DF tree iff d[v] < d[u] < f[u] < f[v]
- $\Rightarrow$  **Parenthesis structure:** If one prints "(u" when discovering u and "u)" when finishing u, then printed text will be a well-formed parenthesized sentence

### DFS Properties (2)

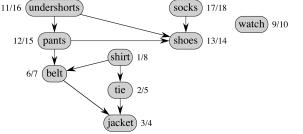
- Classification of edges into groups
  - A tree edge is one in the depth-first forest
  - A back edge (u, v) connects a vertex u to its ancestor v in the DF tree (includes self-loops)
  - A forward edge is a nontree edge connecting a node to one of its DF tree descendants

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- A cross edge goes between non-ancestral edges within a DF tree or between DF trees
- See labels in DFS example
- Example use of this property: A graph has a cycle iff DFS discovers a back edge (application: deadlock detection)
- When DFS first explores an edge (u, v), look at v's color:
  - color[v] == WHITE implies tree edge
  - color[v] == GRAY implies back edge
  - color[v] == BLACK implies forward or cross edge

#### Application: Topological Sort

A directed acyclic graph (dag) can represent precedences: an edge (x, y)implies that event/activity x must occur before y



#### Application: Topological Sort (2)

A **topological sort** of a dag G is an linear ordering of its vertices such that if G contains an edge (u, v), then u appears before v in the ordering

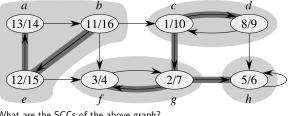
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17/18	11/16	12/15	13/14	9/10	1/8	6/7	2/5	3/4

**Topological Sort Algorithm** 

- 1. Call DFS algorithm on dag G
- 2. As each vertex is finished, insert it to the front of a linked list
- 3. Return the linked list of vertices
- Thus topological sort is a descending sort of vertices based on DFS ► finishing times
- What is the time complexity?
- Why does it work?
  - ▶ When a node is finished, it has no unexplored outgoing edges; i.e., all its descendant nodes are already finished and inserted at later spot in final sort

#### Application: Strongly Connected Components

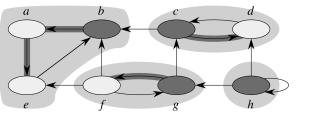
Given a directed graph G = (V, E), a strongly connected component (SCC) of G is a maximal set of vertices  $C \subseteq V$  such that for every pair of vertices  $u, v \in C$  u is reachable from v and v is reachable from u



What are the SCCs of the above graph?

#### Transpose Graph

- Our algorithm for finding SCCs of G depends on the **transpose** of G, denoted  $G^{\mathsf{T}}$
- $G^{\mathsf{T}}$  is simply G with edges reversed
- Fact:  $G^{\mathsf{T}}$  and G have same SCCs. Why?



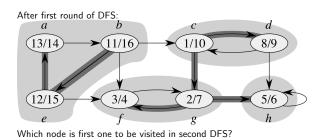
#### SCC Algorithm

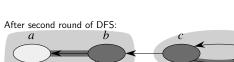
1. Call DFS algorithm on G

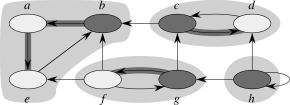
SCC Algorithm Example (2)

- 2. Compute  $G^{\mathsf{T}}$
- 3. Call DFS algorithm on  $G^{\mathsf{T}}$ , looping through vertices in order of decreasing finishing times from first DFS call
- 4. Each DFS tree in second DFS run is an SCC in G

#### SCC Algorithm Example







#### SCC Algorithm Analysis

- What is its time complexity?
- ► How does it work?

  - 1. Let x be node with highest finishing time in first DFS 2. In  $G^{T}$ , x's component C has no edges to any other component (Lemma
  - 22.14), so the second DFS's tree edges define exactly x's component 3. Now let x' be the next node explored in a new component C'
  - 4. The only edges from C' to another component are to nodes in C, so the
  - DFS tree edges define exactly the component for x'
  - 5. And so on...

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