# Computer Science & Engineering 423/823 Design and Analysis of Algorithms

Lecture 04 — Minimum-Weight Spanning Trees (Chapter 23)

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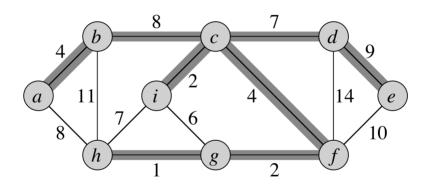
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#### Introduction

- ▶ Given a connected, undirected graph G = (V, E), a **spanning tree** is an acyclic subset  $T \subseteq E$  that connects all vertices in V
  - ightharpoonup T acyclic  $\Rightarrow$  a tree
  - T connects all vertices ⇒ spans G
- ▶ If G is weighted, then T's weight is  $w(T) = \sum_{(u,v) \in T} w(u,v)$
- ► A minimum weight spanning tree (or minimum spanning tree, or MST) is a spanning tree of minimum weight
  - Not necessarily unique
- ▶ Applications: anything where one needs to connect all nodes with minimum cost, e.g. wires on a circuit board or fiber cable in a network

## MST Example



#### Kruskal's Algorithm

- ► Greedy algorithm: Make the locally best choice at each step
- Starts by declaring each vertex to be its own tree (so all nodes together make a forest)
- ▶ Iteratively identify the minimum-weight edge (u, v) that connects two distinct trees, and add it to the MST T, merging u's tree with v's tree

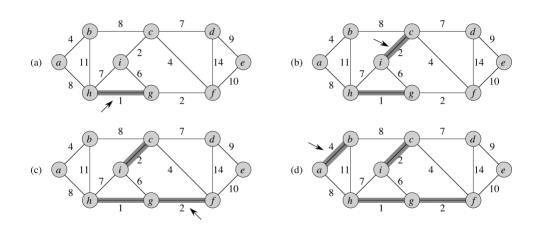
#### MST-Kruskal(G, w)

```
A = \emptyset
1 for each vertex v \in V do
     Make-Set(v)
3 end
4 sort edges in E into nondecreasing order by weight w
5 for each edge (u, v) \in E, taken in nondecreasing order
  do
      if FIND-SET(u) \neq FIND-SET(v) then
     A = A \cup \{(u, v)\}
     Union(u, v)
10 end
11 return A
```

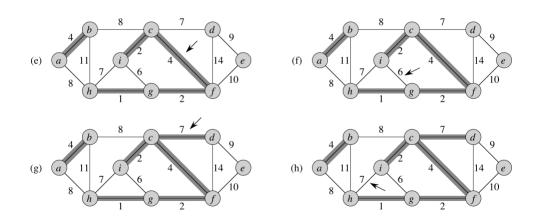
#### More on Kruskal's Algorithm

- ► FIND-SET(u) returns a representative element from the set (tree) that contains u
- ▶ UNION(u, v) combines u's tree to v's tree
- ▶ These functions are based on the **disjoint-set data structure**
- More on this later

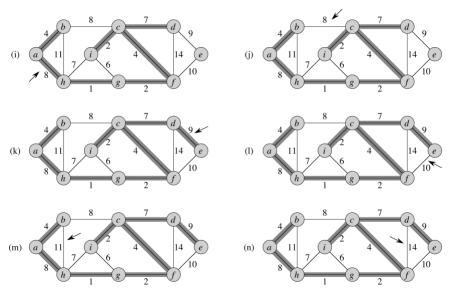
### Example (1)



## Example (2)



## Example (3)



#### Disjoint-Set Data Structure

- ▶ Given a **universe**  $U = \{x_1, ..., x_n\}$  of elements (e.g. the vertices in a graph G), a DSDS maintains a collection  $S = \{S_1, ..., S_k\}$  of disjoint sets of elements such that
  - ▶ Each element  $x_i$  is in exactly one set  $S_i$
  - No set S<sub>j</sub> is empty
- Membership in sets is dynamic (changes as program progresses)
- ▶ Each set  $S \in S$  has a **representative element**  $x \in S$
- Chapter 21

### Disjoint-Set Data Structure (2)

- ▶ DSDS implementations support the following functions:
  - ► Make-Set(x) takes element x and creates new set {x}; returns pointer to x as set's representative
  - ▶ UNION(x, y) takes x's set ( $S_x$ ) and y's set ( $S_y$ , assumed disjoint from  $S_x$ ), merges them, destroys  $S_x$  and  $S_y$ , and returns representative for new set from  $S_x \cup S_y$
  - FIND-SET(x) returns a pointer to the representative of the unique set that contains x
- ▶ Section 21.3: can perform d D-S operations on e elements in time  $O(d \alpha(e))$ , where  $\alpha(e) = o(\lg^* e) = o(\log e)$  is *very* slowly growing:

$$\alpha(e) = \begin{cases} 0 & \text{if } 0 \le e \le 2\\ 1 & \text{if } e = 3\\ 2 & \text{if } 4 \le e \le 7\\ 3 & \text{if } 8 \le e \le 2047\\ 4 & \text{if } 2048 \le e \le 16^{512} \end{cases}$$

#### Analysis of Kruskal's Algorithm

- ▶ Sorting edges takes time  $O(|E| \log |E|)$
- Number of disjoint-set operations is O(|V|+|E|) on O(|V|) elements, which can be done in time  $O((|V|+|E|)\alpha(|V|)) = O(|E|\alpha(|V|))$  since  $|E| \ge |V| 1$
- ► Since  $\alpha(|V|) = o(\log |V|) = O(\log |E|)$ , we get total time of  $O(|E|\log |E|) = O(|E|\log |V|)$  since  $\log |E| = O(\log |V|)$

#### Prim's Algorithm

- ▶ Greedy algorithm, like Kruskal's
- ▶ In contrast to Kruskal's, Prim's algorithm maintains a single tree rather than a forest
- Starts with an arbitrary tree root r
- ► Repeatedly finds a minimum-weight edge that is incident to a node not yet in tree

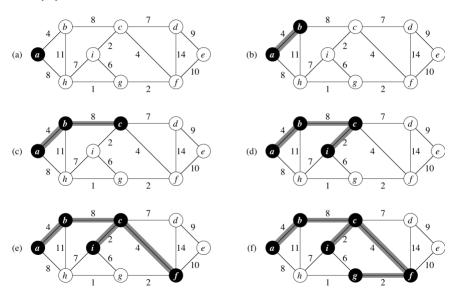
#### MST-Prim(G, w, r)

```
A = \emptyset
1 for each vertex v \in V do
       key[v] = \infty
     \pi[v] = NIL
4 end
 5 key[r] = 0
6 Q = V
7 while Q \neq \emptyset do
        u = \text{Extract-Min}(Q)
        for each v \in Adj[u] do
             if v \in Q and w(u, v) < key[v] then
10
11
                 key[v] = w(u, v)
12
13
        end
14
15 end
```

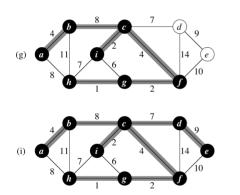
#### More on Prim's Algorithm

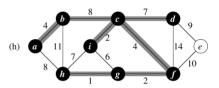
- $\blacktriangleright$  key[v] is the weight of the minimum weight edge from v to any node already in MST
- ► EXTRACT-MIN uses a **minimum heap** (minimum priority queue) data structure
  - lacktriangle Binary tree where the key at each node is  $\leq$  keys of its children
  - Thus minimum value always at top
  - Any subtree is also a heap
  - ► Height of tree is | lg *n* |
  - ▶ Can build heap on n elements in O(n) time
  - ► After returning the minimum, can filter new minimum to top in time  $O(\log n)$
  - ▶ Based on Chapter 6

## Example (1)



## Example (2)





#### Analysis of Prim's Algorithm

- ▶ **Invariant:** Prior to each iteration of the while loop:
  - 1. Nodes already in MST are exactly those in  $V \setminus Q$
  - 2. For all vertices  $v \in Q$ , if  $\pi[v] \neq \text{NIL}$ , then  $key[v] < \infty$  and key[v] is the weight of the lightest edge that connects v to a node already in the tree
- Time complexity:
  - ▶ Building heap takes time O(|V|)
  - ▶ Make |V| calls to EXTRACT-MIN, each taking time  $O(\log |V|)$
  - ▶ For loop iterates O(|E|) times
    - In for loop, need constant time to check for queue membership and  $O(\log |V|)$  time for decreasing v's key and updating heap
  - ▶ Yields total time of  $O(|V| \log |V| + |E| \log |V|) = O(|E| \log |V|)$
  - ▶ Can decrease total time to  $O(|E| + |V| \log |V|)$  using Fibonacci heaps