# CSCE 478/878 Lecture 5: Evaluating Hypotheses

Stephen D. Scott (Adapted from Tom Mitchell's slides)

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#### **Outline**

- Sample error vs. true error
- Confidence intervals for observed hypothesis error
- Estimators
- Binomial distribution, Normal distribution, Central Limit Theorem
- Paired t tests
- Comparing learning methods
- ROC analysis

#### Two Definitions of Error

• The <u>true error</u> of hypothesis h with respect to target function f and distribution  $\mathcal{D}$  is the probability that h will misclassify an instance drawn at random according to  $\mathcal{D}$ .

$$error_{\mathcal{D}}(h) \equiv \Pr_{x \in \mathcal{D}}[f(x) \neq h(x)]$$

• The <u>sample error</u> of h with respect to target function f and data sample S (|S| = n) is the proportion of examples h misclassifies

$$error_S(h) \equiv \frac{1}{n} \sum_{x \in S} \delta(f(x) \neq h(x)),$$

where  $\delta(f(x) \neq h(x))$  is 1 if  $f(x) \neq h(x)$ , and 0 otherwise.

• How well does  $error_{\mathcal{D}}(h)$  estimate  $error_{\mathcal{D}}(h)$ ?

# **Problems Estimating Error**

• Bias: If S is training set,  $error_S(h)$  is optimistically biased

$$bias \equiv E[error_S(h)] - error_D(h)$$

For unbiased estimate (bias = 0), h and S must be chosen independently  $\Rightarrow$  Don't test on training set!

Don't confuse with inductive bias!

• <u>Variance</u>: Even with unbiased S,  $error_S(h)$  may still vary from  $error_D(h)$ 

#### **Estimators**

# **Experiment:**

- 1. Choose sample S of size n according to distribution  $\mathcal{D}$
- 2. Measure  $error_S(h)$

 $error_S(h)$  is a random variable (i.e., result of an experiment)

 $error_S(h)$  is an <u>unbiased estimator</u> for  $error_{\mathcal{D}}(h)$ 

Given observed  $error_S(h)$ , what can we conclude about  $error_D(h)$ ?

#### **Confidence Intervals**

lf

- S contains n examples, drawn independently of h and each other
- n ≥ 30

#### Then

• With approximately 95% probability,  $error_{\mathcal{D}}(h)$  lies in interval

$$error_S(h) \pm 1.96\sqrt{\frac{error_S(h)(1 - error_S(h))}{n}}$$

E.g. hypothesis h misclassifies 12 of the 40 examples in test set S:

$$error_S(h) = \frac{12}{40} = 0.30$$

Then with approx. 95% confidence,  $error_{\mathcal{D}}(h) \in [0.158, 0.442]$ 

#### **Confidence Intervals**

(cont'd)

lf

- S contains n examples, drawn independently of h and each other
- n ≥ 30

#### Then

• With approximately N% probability,  $error_{\mathcal{D}}(h)$  lies in interval

$$error_S(h) \pm z_N \sqrt{\frac{error_S(h)(1 - error_S(h))}{n}}$$

#### where

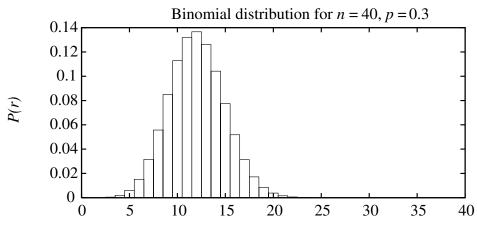
N%:	50%	68%	80%	90%	95%	98%	99%
$z_N$ :	0.67	1.00	1.28	1.64	1.96	2.33	2.58

# Why?

# $error_S(h)$ is a Random Variable

Repeatedly run the experiment, each with different randomly drawn S (each of size n)

Probability of observing r misclassified examples:

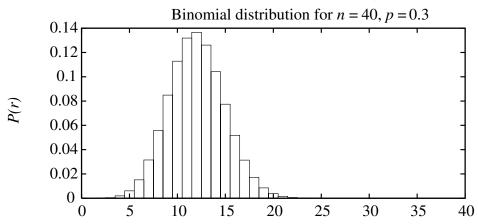


$$P(r) = \binom{n}{r} error_{\mathcal{D}}(h)^r (1 - error_{\mathcal{D}}(h))^{n-r}$$

I.e. let  $error_{\mathcal{D}}(h)$  be probability of heads in biased coin, the P(r) = prob. of getting r heads out of n flips

What kind of distribution is this?

# **Binomial Probability Distribution**



$$P(r) = \binom{n}{r} p^r (1-p)^{n-r} = \frac{n!}{r!(n-r)!} p^r (1-p)^{n-r}$$

Probability P(r) of r heads in n coin flips, if p = Pr(heads)

• Expected, or mean value of X, E[X] (= # heads on n flips = # mistakes on n test exs), is

$$E[X] \equiv \sum_{i=0}^{n} iP(i) = np = n \cdot error_{\mathcal{D}}(h)$$

Variance of X is

$$Var(X) \equiv E[(X - E[X])^2] = np(1 - p)$$

• Standard deviation of X,  $\sigma_X$ , is

$$\sigma_X \equiv \sqrt{E[(X - E[X])^2]} = \sqrt{np(1-p)}$$

# **Approximate Binomial Dist. with Normal**

 $error_S(h) = r/n$  is binomially distributed, with

- mean  $\mu_{error_S(h)} = error_{\mathcal{D}}(h)$  (i.e. unbiased est.)
- standard deviation  $\sigma_{error_S(h)}$

$$\sigma_{error_{S}(h)} = \sqrt{\frac{error_{D}(h)(1 - error_{D}(h))}{n}}$$

(i.e. increasing n decreases variance)

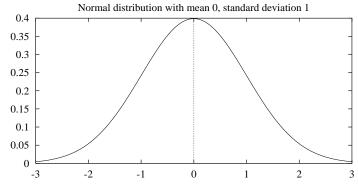
Want to compute confidence interval = interval centered at  $error_{\mathcal{D}}(h)$  containing N% of the weight under the distribution (difficult for binomial)

Approximate binomial by **normal** (Gaussian) dist:

- mean  $\mu_{error_S(h)} = error_{\mathcal{D}}(h)$
- standard deviation  $\sigma_{error_S(h)}$

$$\sigma_{error_S(h)} \approx \sqrt{\frac{error_S(h)(1 - error_S(h))}{n}}$$

# **Normal Probability Distribution**



$$p(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{1}{2} \left(\frac{x-\mu}{\sigma}\right)^2\right)$$

- ullet Defined completely by  $\mu$  and  $\sigma$
- The probability that X will fall into the interval (a,b) is given by

$$\int_{a}^{b} p(x) dx$$

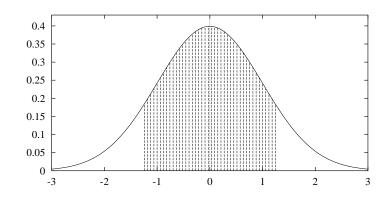
• Expected, or mean value of X, E[X], is

$$E[X] = \mu$$

- Variance of X is  $Var(X) = \sigma^2$
- Standard deviation of X,  $\sigma_X$ , is

$$\sigma_X = \sigma$$

# Normal Probability Distribution (cont'd)

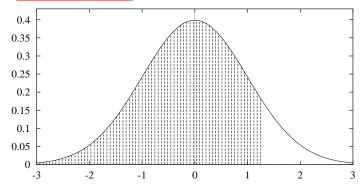


80% of area (probability) lies in  $\mu \pm 1.28\sigma$ 

N% of area (probability) lies in  $\mu \pm z_N\,\sigma$ 

N%:							
$z_N$ :	0.67	1.00	1.28	1.64	1.96	2.33	2.58

Can also have one-sided bounds:



N% of area lies  $<\mu+z_N'\,\sigma$  or  $>\mu-z_N'\sigma$  , where  $z_N'=z_{100-(100-N)/2}$ 

N%:							
$z_N'$ :	0.0	0.47	0.84	1.28	1.64	2.05	2.33

#### **Confidence Intervals Revisited**

lf

- S contains n examples, drawn independently of h and each other
- n ≥ 30

#### Then

ullet With approximately 95% probability,  $error_S(h)$  lies in interval

$$error_{\mathcal{D}}(h) \pm 1.96\sqrt{\frac{error_{\mathcal{D}}(h)(1 - error_{\mathcal{D}}(h))}{n}}$$

Equivalently,  $error_{\mathcal{D}}(h)$  lies in interval

$$error_{S}(h) \pm 1.96\sqrt{\frac{error_{\mathcal{D}}(h)(1 - error_{\mathcal{D}}(h))}{n}}$$

which is approximately

$$error_S(h) \pm 1.96\sqrt{\frac{error_S(h)(1 - error_S(h))}{n}}$$

(One-sided bounds yield upper or lower error bounds)

#### **Central Limit Theorem**

How can we justify approximation?

Consider a set of independent, identically distributed random variables  $Y_1 \dots Y_n$ , all governed by an <u>arbitrary</u> probability distribution with mean  $\mu$  and finite variance  $\sigma^2$ . Define the sample mean

$$\bar{Y} \equiv \frac{1}{n} \sum_{i=1}^{n} Y_i$$

Note that  $\bar{Y}$  is itself a random variable, i.e. the result of an experiment (e.g.  $error_S(h) = r/n$ )

Central Limit Theorem: As  $n \to \infty$ , the distribution governing  $\bar{Y}$  approaches a Normal distribution, with mean  $\mu$  and variance  $\sigma^2/n$ 

Thus the distribution of  $error_S(h)$  is approximately normal for large n, and its expected value is  $error_D(h)$ 

(Rule of thumb:  $n \geq 30$  when estimator's distribution is binomial, might need to be larger for other distributions)

# **Calculating Confidence Intervals**

- 1. Pick parameter p to estimate
  - $error_{\mathcal{D}}(h)$
- 2. Choose an estimator
  - $\bullet$   $error_S(h)$
- 3. Determine probability distribution that governs estimator
  - $error_S(h)$  governed by binomial distribution, approximated by normal when  $n \geq 30$
- 4. Find interval (L,U) such that N% of probability mass falls in the interval
  - Could have  $L = -\infty$  or  $U = \infty$
  - Use table of  $z_N$  or  $z_N'$  values (if distrib. normal)

# **Difference Between Hypotheses**

Test  $h_1$  on sample  $S_1$ , test  $h_2$  on  $S_2$ ,  $S_1 \cap S_2 = \emptyset$ 

1. Pick parameter to estimate

$$d \equiv error_{\mathcal{D}}(h_1) - error_{\mathcal{D}}(h_2)$$

Choose an estimator

$$\widehat{d} \equiv error_{S_1}(h_1) - error_{S_2}(h_2)$$
 (unbiased)

3. Determine probability distribution that governs estimator (difference between two normals is also normal, variances add)

$$\sigma_{\widehat{d}} pprox \sqrt{rac{error_{S_1}(h_1)(1-error_{S_1}(h_1))}{n_1} + rac{error_{S_2}(h_2)(1-error_{S_2}(h_2))}{n_2}}$$

4. Find interval (L,U) such that N% of prob. mass falls in the interval:  $\widehat{d}\pm z_n\,\sigma_{\widehat{d}}$ 

(Can also use  $S = S_1 \cup S_2$  to test  $h_1$  and  $h_2$ , but not as accurate; interval overly conservative)

# Paired t test to compare $h_A$ , $h_B$

- 1. Partition data into k disjoint test sets  $T_1, T_2, \ldots, T_k$  of equal size, where this size is at least 30
- 2. For i from 1 to k, do

$$\delta_i \leftarrow error_{T_i}(h_A) - error_{T_i}(h_B)$$

3. Return the value  $\bar{\delta}$ , where

$$\bar{\delta} \equiv \frac{1}{k} \sum_{i=1}^{k} \delta_i$$

N% confidence interval estimate for d:

$$\bar{\delta} \pm t_{N,k-1} s_{\bar{\delta}}$$

$$s_{\bar{\delta}} \equiv \sqrt{\frac{1}{k(k-1)} \sum_{i=1}^{k} (\delta_i - \bar{\delta})^2}$$

t plays role of z, s plays role of  $\sigma$ 

t test gives more accurate results since std. deviation approximated and test sets for  $h_A$  and  $h_B$  not independent

# Comparing Learning Algorithms $\mathcal{L}_A$ and $\mathcal{L}_B$

What we'd like to estimate:

$$E_{S\subset\mathcal{D}}[error_{\mathcal{D}}(L_A(S)) - error_{\mathcal{D}}(L_B(S))]$$

where L(S) is the hypothesis output by learner L using training set S

I.e., the expected difference in true error between hypotheses output by learners  $L_A$  and  $L_B$ , when trained using randomly selected training sets S drawn according to distribution  $\mathcal{D}$ 

But, given limited data  $D_0$ , what is a good estimator?

• Could partition  $D_0$  into training set  $S_0$  and testing set  $T_0$ , and measure

$$error_{T_0}(L_A(S_0)) - error_{T_0}(L_B(S_0))$$

 Even better, repeat this many times and average the results (next slide)

# Comparing learning algorithms $L_A$ and $L_B$ (cont'd)

#### k-fold Cross Validation

- 1. Partition data  $D_0$  into k disjoint test sets  $T_1, T_2, \ldots, T_k$  of equal size, where this size is at least 30
- 2. For i from 1 to k, do

(use  $T_i$  for the test set, and the remaining data for training set  $S_i$ )

- $S_i \leftarrow D_0 T_i$
- $h_A \leftarrow L_A(S_i)$
- $h_B \leftarrow L_B(S_i)$
- $\delta_i \leftarrow error_{T_i}(h_A) error_{T_i}(h_B)$
- 3. Return the value  $\bar{\delta}$ , where

$$\bar{\delta} \equiv \frac{1}{k} \sum_{i=1}^{k} \delta_i$$

# Comparing learning algorithms $L_A$ and $L_B$ (cont'd)

- Notice we'd like to use the paired t test on  $\overline{\delta}$  to obtain a confidence interval
- Not really correct, because the training sets in this algorithm are not independent (they overlap!)
- More correct to view algorithm as producing an estimate of

$$E_{S \subset D_0}[error_{\mathcal{D}}(L_A(S)) - error_{\mathcal{D}}(L_B(S))]$$

instead of

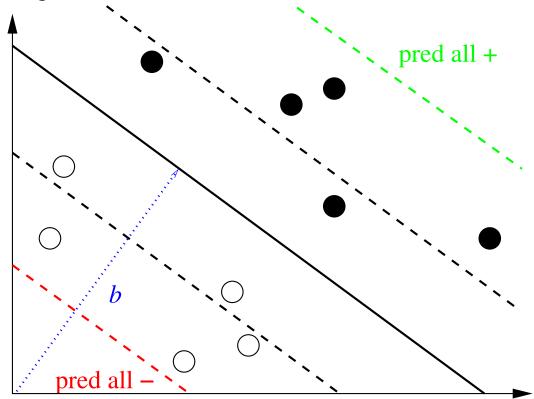
$$E_{S\subset\mathcal{D}}[error_{\mathcal{D}}(L_A(S)) - error_{\mathcal{D}}(L_B(S))]$$

• But even this approximation is better than nothing

- So far, we've looked at a single error rate to compare hypotheses/learning algorithms/etc.
- This may not tell the whole story:
  - 1000 test examples: 20 positive, 980 negative
  - $h_A$  gets 2/20 pos correct, 965/980 neg correct, for accuracy of (2 + 965)/(20 + 980) = 0.967
  - Pretty impressive, except that always predicting negative yields accuracy = 0.980
  - Would we rather have  $h_B$ , which gets 19/20 pos correct and 930/980 neg, for accuracy = 0.949?
  - Depends on how important the positives are, i.e. frequency in practice and/or cost (e.g. cancer diagnosis)
- Can separately report false positive (FP) and false negative (FN) error rates, but we can give even more detail than that

(cont'd)

- Consider an ANN or SVM
- Normally threshold at 0, but what if we changed it?
- Keeping weight vector constant while changing threshold = holding hyperplane's slope fixed while moving along its normal vector

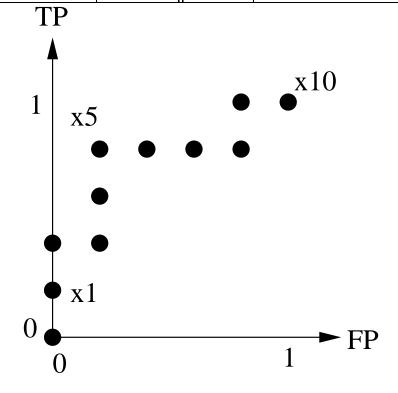


• I.e. get a set of classifiers, one per labeling of test set

## Plotting TP versus FP error

- Consider the "always —" hyp. What is its FP rate? Its TP rate? What about the "always +" hyp?
- In between the extremes, we plot TP versus FP by sorting the test examples by the SVM's weighted sums:

Ex	$\vec{w} \cdot \vec{x}$	label	Ex	$ec{w}\cdotec{x}$	label
$x_1$	169.752	+	$x_6$	-12.640	_
$x_2$	109.200	+	$x_7$	-29.124	_
$x_3$	19.210	_	$x_8$	-83.222	_
$x_4$	1.905	+	$x_9$	-91.554	+
$x_5$	-2.75	+	$x_{10}$	-128.212	_



# ROC Analysis Convex Hull TP ID3 naive Bayes

- The <u>convex hull</u> of the ROC curve yields a collection of classifiers, each optimal under different conditions
  - If FP cost = FN cost, then draw a line with slope |N|/|P| at (0,1) and drag it towards convex hull until you touch it; that's your operating point
  - Can use as a classifier any part of the hull since can randomly select between two classifiers
- Can also compare curves against "single-point" classifiers when no curves available
  - In plot, ID3 better than our SVM iff negatives scarce;
     nB never better

# Miscellany

- What is the worst possible ROC curve?
- One metric for measuring a curve's goodness: <u>area under curve</u> (AUC):

$$\frac{\sum_{x_{+} \in P} \sum_{x_{-} \in N} I(h(x_{+}) > h(x_{-}))}{|P| |N|}$$

i.e. rank all examples by confidence in "+" prediction, count the number of times a positively-labeled example (from P) is ranked above a negatively-labeled one (from N), then normalize

- What is the best value?
- Distribution approximately normal if |P|, |N| > 10, so can find confidence intervals
- Catching on as a better scalar measure of performance than error rate
- ROC analysis possible (though tricky) with multi-class problems

## Miscellany (cont'd)

- Can use ROC curve to modify classifiers, e.g. re-label decision trees
- What does "ROC" stand for?
  - "Receiver Operating Characteristic" from signal detection theory, where binary signals are corrupted by noise
  - Use plots to determine how to set threshold to determine presence of signal
  - Threshold too high: miss true hits (TP rate low), too low: too many false alarms (FP rate high)
- Alternatives to ROC: <u>cost curves</u> and precision-recall curves

Topic summary due in 1 week!