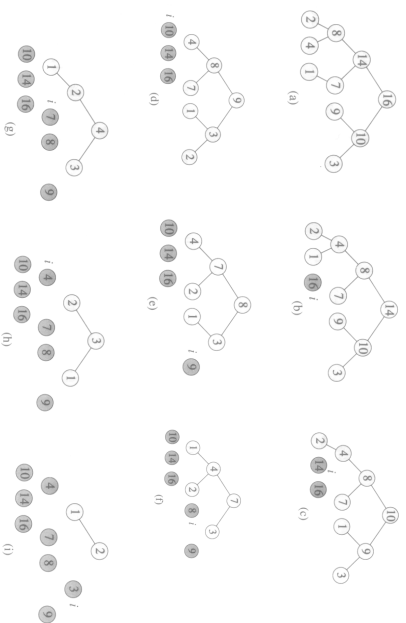


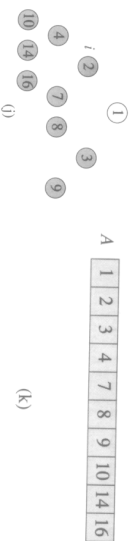
Heapsort: Example $A = \langle 4, 1, 3, 2, 16, 9, 10, 14, 8, 7 \rangle$



3

Heapsort: Example $A = \langle 4, 1, 3, 2, 16, 9, 10, 14, 8, 7 \rangle$

(cont.)



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Heapsort (II)

Textbook, Chapter 7

1

CSCCE310: Data Structures and Algorithms

www.cse.unl.edu/~choueiry/S01-310/

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Heapsort: Principle and algorithm

Input: Array $A[1..n]$, where $n = \text{length}[A]$

1. Build a heap out of the array
the maximum element will be in $A[1]$, it should be last!!
2. Exchange $A[1]$ with $A[n]$
3. Reset heap size to $(n - 1)$
4. Heapify $A[1..(n - 1)]$, repeat... down to a heap of size 2

2

```

HEAPSORT(A)
1 BUILD-HEAP(A)
2 for i ← length[A] downto 2
3   do exchange A[1] ↔ A[i]
4   heap-size[A] ← heap-size[A] - 1
5   HEAPIFY(A, 1)

```

Priority queue: Applications

1. Job scheduling on a shared resource (e.g., computer)
Priority queue keeps track of jobs and their relative importance.
Insert allows us to add new jobs at any time
Extract-Max selects highest priority jobs when current job is finished/interrupted
2. Event-driven simulator
Queue of events to be simulated, each has occurrence time \rightarrow key value

Occurrence of event causes other events to be simulated in future \rightarrow Insert Extract-Min and Minimum instead of Extract-Max and Maximum

Implementation \rightarrow a heap

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Heapsort: Complexity

For an array A of size n

- Build-Heap is called once, its complexity is $O(n)$
- Heapify is called $n - 1$ times, its complexity is $O(\lg n)$
- Complexity of Heapsort is $O(n + (n - 1)\lg n) = O(n \lg n)$

Heapsort: Utility

- Heapsort is an excellent algorithm, however Quicksort is better in practice
- Heap data structure has enormous utility
e.g., efficient priority queue

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Heap-Extract-Max(A)

If $\text{heap-size}[A] < 1$
then error "heap underflow"

$\text{max} \leftarrow A[1]$

$A[1] \leftarrow A[\text{heap-size}[A]]$

$\text{heap-size}[A] \leftarrow \text{heap-size}[A] - 1$

Heapify($A, 1$)

return max

- \rightarrow Returns $A[1]$
- \rightarrow Places the last element of the heap in $A[1]$
- \rightarrow Decrements size of heap
- \rightarrow Heapifies the array
- \rightarrow Running time is in $O(\lg n)$ (constant effort and 1 heapify)

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Priority queue as a data structure

- Data structure for maintaining a set S of elements, each with a value called key
- Supports operations:
Insert(S, x) (i.e., $S \leftarrow S \cup \{x\}$)
Maximum(S) returns element of S with largest key
Extract-Max(S) removes and returns the element of S with largest key

6

Heap as a priority queue

For any set S of n elements:

- **Heap-Maximum**(A) is in $\Theta(1)$
- **Heap-Extract-Max**(A) is in $O(\lg n)$
- **Heap-Insert**(A, key) is in $O(\lg n)$

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Notes of Dr. Cusack

Bubble-sort

- Go through the list in order, swapping two elements if their keys are out of order
- Repeat until no swaps are performed. The list is sorted
- n passes suffice
- Similar to Insertion-sort, but has lots of swaps

Bubble-Sort (A)

For $i \rightarrow n - 1$ downto 1

For $j \rightarrow 1$ to i

When $A[j - 1] > A[j]$, $A[j - 1] \leftrightarrow A[j]$

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Heap-Insert(A, key)

$heap_size[A] \leftarrow heap_size[A] + 1$

$i \leftarrow heap_size[A]$

while $i > 1$ and $A[Parent(i)] < key$

do $A[i] \leftarrow A[Parent(i)]$

$i \leftarrow Parent(i)$

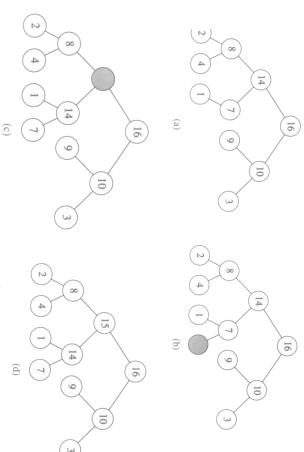
$A[i] \leftarrow key$

→ First expands the heap by adding 1 new leaf
 → Then traverses path from new leaf to root to find a proper place for the new element

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Heap-Insert(A, key): Example

$key = 15$



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Running time is $O(\lg n)$, since path from new leaf to root has length $\lg n$

Name	Upper bound	Lower bound	Tight bound
Selection-sort	$O(n^2)$	$\Omega(n)$	
Insertion-sort	$O(n^2)$	$\Omega(n)$	
Bubble-sort	$O(n^2)$		
Merge-sort			$\Theta(n \lg n)$
Heap-sort	$O(n \lg n)$		
Quick-sort	$O(n^2)$	$\Omega(n \lg n)$	