

Dynamic Programming: Typical use

Optimization problems (vs. decision problems):

- A problem has many solutions
- Each solution has a value (e.g., price, preference)
- Optimization: find solution that has best value (maximization/minimization)
- There could several optimal solutions
- Goal: find one optimal solution

Dynamic Programming (I)

Textbook, Chapter 16, Sections 16.1

CSC310: Data Structures and Algorithms

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How to develop: a Dynamic Programming algorithm

1. Characterize structure of optimal solution
2. Recursively define value of optimal solution
3. Compute value of optimal solution in a bottom-up fashion
4. Construct optimal solution from computed information

Step 4 can be omitted if you are looking only for value of optimal solution

Dynamic Programming

solves problems by combining solutions to subproblems

Divide-&-conquer:

partition problems into independent subproblems
 solve subproblem recursively
 combine solutions to solve initial problem

Dynamic Prog.:

subproblems are not independent, share subsubproblems

Divide-&-conquer would solve common subsubproblems repeatedly

Dynamic Prog. would solve each subsubproblem once and save answer in a table → savings

Matrix multiplication: number of scalar multiplications

MATRIX-MULTIPLY(A, B)

```

1  if columns[A] ≠ rows[B]
2  then error "incompatible dimensions"
3  else for i ← 1 to rows[A]
4        do for j ← 1 to columns[B]
5              do C[i, j] ← 0
6              for k ← 1 to columns[A]
7                do C[i, j] ← C[i, j] + A[i, k] · B[k, j]
8  return C

```

Matrices: A ($p \times q$); B ($q \times r$)

Product: AB ($p \times r$) requires pqr scalar multiplications

Matrix multiplication: Example

Consider: (A_1, A_2, A_3) , with
 dimensions of A_1 are 10×100
 dimensions of A_2 are 100×5
 dimensions of A_3 are 5×50

How many scalar multiplications:

in $((A_1 A_2) A_3) : \dots$
 in $(A_1 (A_2 A_3)) : \dots$

→ Sequence matters

Outline

- \surd Dynamic programming for Matrix multiplication
- Goal: minimize number of scalar multiplications
- \surd 2 key characteristics an optimization problem must satisfy to be solvable with Dynamic Programming
- ? How to find longest common subsequence of 2 sequences
- \times Use of Dynamic Progr. to find an optimal triangulation of a convex polygon (fundamental in Computational Geometry)

Matrix-Chain multiplication

Given: a sequence (A_1, A_2, \dots, A_n) of n matrices

Compute: their product $A_1 A_2 \dots A_n$

How?

- One way:
 Compute $A_1 A_2$, then $(A_1 A_2) A_3$, then $((A_1 A_2) A_3) A_4$, etc.
 - Another way:
 Compute $A_1 A_2$, and $A_3 A_4$, then $(A_1 A_2) (A_3 A_4)$, etc.
 - ... 5 distinct ways, full parenthesizations (FP)
 full parenthesization: single matrix or product of two FP products with parenthesis
- All equivalent? Not in terms of running time

MCM Problem: Brute-force solution no good :-)

Check applicability of DP:

Step 1: Characterize structure of an optimal solution

Check whether an optimal solution contains optimal solutions to subproblems

Step 2: ...

MCM Problem: optimal solution

Notation: result of $A_i A_{i+1} \dots A_j$ is matrix $A_{i\dots j}$

An optimal solution:

- splits $\langle A_1, A_2, \dots, A_n \rangle$ in $\langle A_1, \dots, A_k \rangle$ and $\langle A_{k+1}, \dots, A_n \rangle$ with $1 \leq k < n$
- parenthesize each of $\langle A_1, \dots, A_k \rangle$ and $\langle A_{k+1}, \dots, A_n \rangle$ (by splitting them somehow) to compute the 2 portions $A_{1\dots k}$ and $A_{k+1\dots n}$ and
- Compute product by multiplying the two matrices $A_{1\dots k}$ and $A_{k+1\dots n}$

Matrix-Chain Multiplication Problem (MCM)

Given: a sequence $\langle A_1, A_2, \dots, A_n \rangle$ of n matrices each A_i has dimensions $p_{i-1} \times p_i$

Task: Fully parenthesize their product $A_1 A_2 \dots A_n$

Objective: while minimizing the number of scalar multiplications

MCM Problem: Brute-force solution

- Compute all possible full parenthesizations (exhaustive search)
- Compute number of scalar multiplications for each
- Choose (any) one with the minimum such value

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Is this a feasible solution?

Number of possible full parenthesizations (by solving recurrence)

$$P(n) = \frac{1}{n} \binom{2(n-1)}{n-1} = \Omega(4^n / n^{3/2})$$

Exponential in n , thus avoid!

Dynamic Programming: structure of optimal solution (II)
(restatement)

To compute an optimal solution of a problem of size k

- Compute all solutions to problem using the optimal solutions of subproblems of size $k - 1$
- Determine the optimum

Key question: define value of optimal solution

Step 2: Define value of an optimal solution recursively in terms of the optimal solutions to subproblems

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MCM Problem: A recursive solution (I)

- Consider the chain: $\langle A_1, A_2, \dots, A_n \rangle$
- Consider a subproblem: $A_i A_{i+1} \dots A_j$ with $1 \leq i \leq j \leq n$
- Let $m[i, j]$ be cost of computing $A_{i..j}$

Task: define $m[i, j]$ recursively

- $i = j, A_{i..i} = A_i$: no scalar multiplication required
 $\Rightarrow m[i, i] = 0$ for $i = 1, 2, \dots, m$
- $i < j$, exploit structure of optimal solution (**Step 1**)
 Assume A_i, \dots, A_j is split in A_i, \dots, A_k and $A_{k+1} \dots A_j$ with
 $i \leq k < j$

Then, $m[i, j] = \min$ cost of computing $A_{i..k}$ + that of $A_{k+1..j}$ + cost of multiplying $A_{i..k}$ and $A_{k+1..j}$

So, $m[i, j] = m[i, k] + m[k+1, j] + p_{i-1} p_k p_j$ with
 $k = i, i+1, \dots, j-1$

Check $m[i, j]$ for all k ($(j - i)$ possibilities); choose the minimum

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MCM Problem: structure of optimal solution

An optimal solution by splitting $\langle A_1, A_2, \dots, A_n \rangle$ in $\langle A_1, \dots, A_k \rangle$ and $\langle A_{k+1}, \dots, A_n \rangle$ with $1 \leq k < n$

Observation: parenthesization of each portion must be optimal

Justification: If there were a better FP $A_1 A_2 \dots A_k$, choosing it would yield a better FP of $\langle A_1, A_2, \dots, A_n \rangle$, which is an optimum. Contradiction

Conclusion: optimal solution contains within it optimal subproblems

Retain: First hallmark of applicability of Dynamic Prog
 \rightarrow optimal substructure within optimal solution

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April 4, 2001

Dynamic Programming: structure of optimal solution (I)

- To compute an optimal solution, compute all optimal subproblems
- Start with all optimal subproblems of size 1
- Compute all optimal subproblems of size 2 using the optimal subproblems of size 1
- Repeat until getting an optimal subproblem of size n , which is an optimal solution

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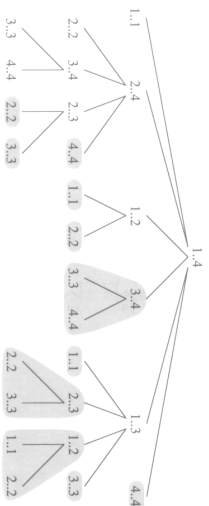
MCM Problem: optimal solution

$$m[i, j] = \begin{cases} 0 & \text{if } i = j \\ \min_{i \leq k < j} \{m[i, k] + m[k + 1, j] + p_{i-1}p_k p_j\} & \text{if } i < j \end{cases}$$

Two alternatives:

1. Compute $m[1, n]$ with a recursive algorithm (i.e., top-down)
→ Recursion tree
2. Compute $m[i, j]$ in a bottom-up fashion
→ **Step 3**

MCM Problem: recursion tree, example: $m[1, 4]$



Recursion algorithms may encounter each subproblem many times in different branches. Its complexity is:

$$T(n) \geq 1 + \sum_{k=1}^{n-1} (T(k) + T(n-k) + 1) \text{ for } n > 1$$

Solution: $T(n) \geq 2^{n-1} = \Omega(2^n)$, using substitution method

Exponential :-(

Optimized thanks to memoization :-)

MCM Problem: A recursive solution (II)

$$m[i, j] = \begin{cases} 0 & \text{if } i = j \\ \min_{i \leq k < j} \{m[i, k] + m[k + 1, j] + p_{i-1}p_k p_j\} & \text{if } i < j \end{cases}$$

Let $s[i, j]$ be the value of k corresponding to the minimum

Now, $s[i, j]$ tells us where to split problem $A_i A_{i+1} \dots A_j$ so that the cost $m[i, j]$ of computing $A_i A_{i+1} \dots A_j$ is optimal (i.e., minimal)

MCM Problem: number of possible subproblems

Each $A_i A_{i+1} \dots A_j$ is possible subproblem

How many subproblems, knowing $1 \leq i \leq j \leq n$?

1. for $i < j$, $\binom{n}{2} = \frac{n(n-1)}{2}$ possibilities

and $i = j$, n possibilities

Thus $\frac{n(n+1)}{2} = \Theta(n^2)$ subproblems

2. Alternatively, $\sum_{x=1}^n x = \frac{n(n+1)}{2} = \Theta(n^2)$

We have to compute $\Theta(n^2)$ in total

MCM Problem: alternative to recursive algorithm

Step 3: Compute value of an optimal solution bottom-up

- Dimensions of A_i are $p_{i-1}p_i$, for $i = 1, \dots, n$
- Input: $\langle p_0, p_1, p_2, \dots, p_n \rangle$ of length $n + 1$
Example: $\langle 30, 35, 15, 5, 10, 20, 25 \rangle$ is the sequence of 6 matrices of dimensions 30×35 (A_1), 35×15 (A_2), 15×5 (A_3), 5×10 (A_4), 10×20 (A_5), 20×25 (A_6)
- Use auxiliary table $m[1 \dots n, 1 \dots n]$ for storing $m[i, j]$ (i.e., costs). Example: $m[6, 6]$
- Use auxiliary table $s[1 \dots n, 1 \dots n]$ to record index k that achieved optimal cost in computing $m[i, j]$ for constructing optimal solution, in Step 4
Example: $s[6, 6]$

MCM Problem: bottom-up algorithm

```

1  n ← length[p] - 1
2  for i ← 1 to n
3    do m[i, i] ← 0
4  for l ← 2 to n
5    do for i ← 1 to n - l + 1
6      do j ← i + l - 1
7        m[i, j] ← ∞
8        for k ← i to j - 1
9          do q ← m[i, k] + m[k + 1, j] + pi-1pkpj
10         if q < m[i, j]
11           then m[i, j] ← q
12         s[i, j] ← k
13  return m and s

```

Memorization

A technique of Computer Science to speed up programs by saving the results of computation.

The basic idea of memo functions is to accumulate a database of input/output pairs; when the function is called, it first check the database and see if it can avoid solving the problem from scratch.

Adapted from:

Artificial Intelligence: A Modern Approach
Russel & Norvig

MCM Problem: recursion algorithm

```

Recursive-MATRIX-CHAIN(p, i, j)
1  if i = j
2    then return 0
3  m[i, j] ← ∞
4  for k ← i to j - 1
5    do q ← Recursive-MATRIX-CHAIN(p, i, k)
6       + Recursive-MATRIX-CHAIN(p, k + 1, j) + pi-1pkpj
7       if q < m[i, j]
8         then m[i, j] ← q

```

Retains: Second hallmark of applicability of Dynamic Prog.
→ overlapping subproblems in recursive (top-down) algorithm

Line 9: computes $m[i, j]$ using

$$m[i, j] = \min_{i \leq k < j} \{m[i, k] + m[k+1, j] + p_{i-1}k p_j\}$$

For instance, for $m[2, 5]$, $l = 4$, $2 \leq k < 5$ we compute the

minimum of: $\begin{cases} m[2, 2] + m[3, 5] + p_1 p_2 p_5 \\ m[2, 3] + m[4, 5] + p_1 p_3 p_5 \\ m[2, 4] + m[5, 5] + p_1 p_4 p_5 \end{cases}$

$m[2, 2]$, $m[5, 5]$ ($= 0$) were computed when $l = 1$

$m[2, 3]$, $m[4, 5]$ were computed for $l = 2$

$m[2, 4]$, $m[3, 5]$ were computed for $l = 3$ So, for each $m[i, j]$, we need $m[i, k]$, $m[k+1, j]$ that were computed at previous step.

MCM Problem: bottom-up algorithm (II)

Fills up m by solving the parenthesization problem on chains of increasing length:

- all chains of length $l = 1$, $m[i, i]$,
- all chains of length $l = 2$, $m[i, i+1]$,
- all chains of length $l = 3$, $m[i, i+2]$,
- all chains of length \dots ,
- all chains of length $l = n$, $m[i, i+n-1]$.

Line 12: Keeps track of k corresponding to minimum in $s[i, j]$

For example, for $s[2, 5] = 3$ (useful for reconstructing solution)

This means: optimal parenthesization of $A_2 A_3 A_4 A_5$ is $(A_2 A_3 A_4) A_5$

Time: Loops nested three deep $(l, i, k) \rightarrow O(n^3)$ (actually $\Theta(n^3)$)

Space: $\Theta(n^2)$ to store $m[i, j]$ and $s[i, j]$

Conclusion: Matrix-Chain-Order is much more efficient than exponential-time brute-force solution (i.e., enumerating all possible FPs, computing their value, choosing the best one.)

MCM Problem: bottom-up algorithm (III)

Lines 2-3: $m[i, i] \leftarrow 0$, chains of length 1

Line 4: l all chain lengths from 2 to n

Loop 4-12: 1. $l = 2$, we compute $m[i, i+1]$ for $1 \leq i \leq (n-1)$, that is, for $n = 6$, $m[1, 2]$, $m[2, 3]$, $m[3, 4]$, $m[4, 5]$, $m[5, 6]$ ('second' diagonal)

2. $l = 3$, we compute $m[i, i+2]$ for $1 \leq i \leq (n-2)$, that is, $m[1, 3]$, $m[2, 4]$, $m[3, 5]$, $m[4, 6]$

3. $l = 4$, we compute $m[i, i+3]$ for $1 \leq i \leq (n-3)$, that is, $m[1, 4]$, $m[2, 5]$, $m[3, 6]$

4. $l = 5$, we compute $m[i, i+4]$ for $1 \leq i \leq (n-4)$, that is, $m[1, 5]$, $m[2, 6]$

5. $l = 6$, we compute $m[i, i+5]$ for $1 \leq i \leq (n-5)$, that is, $m[1, 6]$

Matrix-Chain-Multiply($A, s, 1, 6$)
 $i = 1, j = 6$
 $X \rightarrow (A, s, 1, s[1, 6] = 3)$
 $i = 1, j = 3$
 $X \rightarrow (A, s, 1, s[1, 3] = 1)$ returns A_1
 $Y \rightarrow (A, s, s[1, 3] + 1 = 2, 3)$
 $i = 2, j = 3$
 $X \rightarrow (A, s, 2, s[2, 3] = 2)$ returns A_2
 $Y \rightarrow (A, s, s[2, 3] + 1 = 3, 3)$ returns A_3
 returns $A_2 A_3$
 returns $A_1 (A_2 A_3)$
 $Y \rightarrow (A, s, s[1, 6] + 1 = 4, 6)$
 $i = 4, j = 6$
 $X \rightarrow (A, s, 1, 4, s[4, 6] = 5)$
 $i = 4, j = 5$
 $X \rightarrow (A, s, 1, 4, s[4, 5] = 4)$ returns A_4
 $Y \rightarrow (A, s, 1, s[4, 5] + 1 = 5, 5)$ returns A_5
 returns $A_4 A_5$
 $Y \rightarrow (A, s, 1, s[4, 6] + 1 = 6, 6)$ returns A_6
 returns $(A_4 A_5) A_6$
 returns $(A_1 (A_2 A_3)) ((A_4 A_5) A_6)$

Elements of Dynamic Programming

Applicability (hallmarks)

1. Optimal substructure within optimal solution
2. Overlapping subproblems in recursive (top-down) algorithm

MCM: Constructing optimal solution

Matrix-Chain-Order determines value of optimal solution but not does not directly show multiplication order

Step 4: constructs optimal solution using $s[1 \dots n, 1 \dots n]$

Each $s[i, j]$ records k for optimal parenthesization of $A_i A_{i+1} \dots A_j$
 $\rightarrow k$ splits $A_i A_k$ into $A_{k+1} \dots A_j$

MCM is optimal for $A_1 \dots s[1, n] A_{s[1, n]+1} \dots n$

Earlier matrix multiplications can be computed recursively

Optimal solution is constructed with Matrix-Chain-Multiply

MCM: Constructing optimal solution

First, call Matrix-Chain-Multiply($A, s, 1, n$)

```

Matrix-Chain-Multiply( $A, s, i, j$ )
1  if  $j > i$ 
2  then  $X \leftarrow$  Matrix-Chain-Multiply( $A, s, i, s[i, j]$ )
3   $Y \leftarrow$  Matrix-Chain-Multiply( $A, s, s[i, j] + 1, j$ )
4  return Matrix-Chain-Multiply( $X, Y$ )
5  else return  $A_i$ 

```


Summary

MCM problem solved either by :

- a bottom-up dynamic programming algorithm
- a top-down (recursive) memorized algorithm in $O(n^3)$, where n is the number of matrices in chain

Optimal substructure

- a problem exhibits optimal substructure when optimal solution contains within it optimal solutions to subproblems
- Strategy: assume there is a better solution to a subproblem and show this assumption contradicts optimality of the solution to original problem
- Choice of subproblem remains an art and determines performance of the algorithm

Overlapping subproblems

Space of subproblems must be small

- Better reuse few subproblems then generate and solve more subproblems
- Typically, total number of distinct subproblems polynomial in size of input