Title: Local Search

Required reading: AIMA, Chapter 4 (Section 4.1)

LWH: Chapters 6, 10, 13 and 14.

Introduction to Artificial Intelligence CSCE 476-876, Fall 2023

URL: www.cse.unl.edu/~choueiry/F23-476-876

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# Outline Iterative improvement search:

- Hill-climbing
- Simulated annealing
- ...

2- Systematic/constructive vs. iterative improvement

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# Iterative improvement (a.k.a. local search)

— Sometimes, the 'path' to the goal is irrelevant only the state description (or its quality) is needed

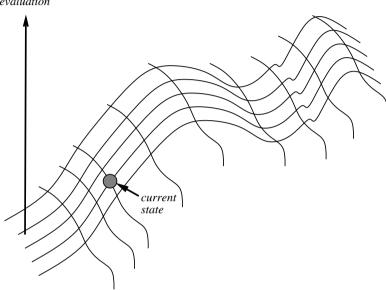
#### Iterative improvement search

- choose a single current state, sub-optimal
- gradually modify current state
- generally visiting 'neighbors'
- until reaching a near-optimal state

**Example:** complete-state formulation of N-queens

# Main advantages of local search techniques

- 1. Memory (usually a constant amount)
- 2. Find reasonable solutions in large spaces where we cannot possibly search the space exhaustively
- 3. Useful for optimization problems: best state given an objective function (quality of the goal)



- All states are layed up on the surface of a landscape
- A state's location determines its neighbors (where it can move)
- A state's elevation represents its quality (value of objective function)
- Move from one neighbor of the current state to another state until reaching the highest peak

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#### Two major classes

- 1. Hill climbing (a.k.a. gradient ascent/descent)
  - $\rightarrow$  try to make changes to improve quality of current state
- 2. Simulated Annealing (physics)
  - $\rightarrow$  things can temporarily get worse

Others: tabu search, local beam search, genetic algorithms, etc.

- → Optimality (soundness)? Completeness?
- $\longrightarrow$  Complexity: space? time?
- $\longrightarrow$  In practice, surprisingly good..

(eroding myth)

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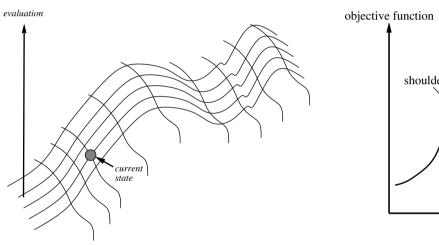
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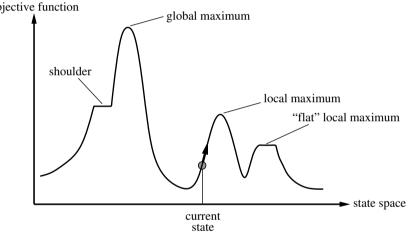
# Hill climbing

Start from any state at random and loop:

Examine all direct neighbors

If a neighbor has higher value then move to it else exit





Problems:

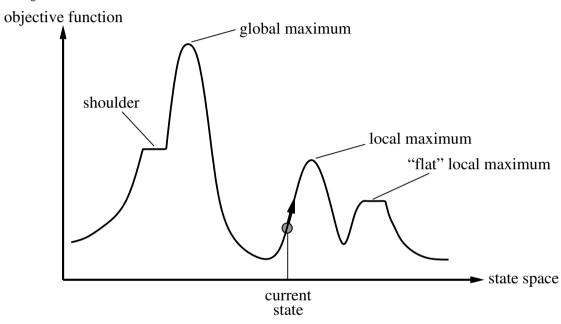
Local optima: (maxima or minima) search halts

Plateau: flat local optimum or shoulder

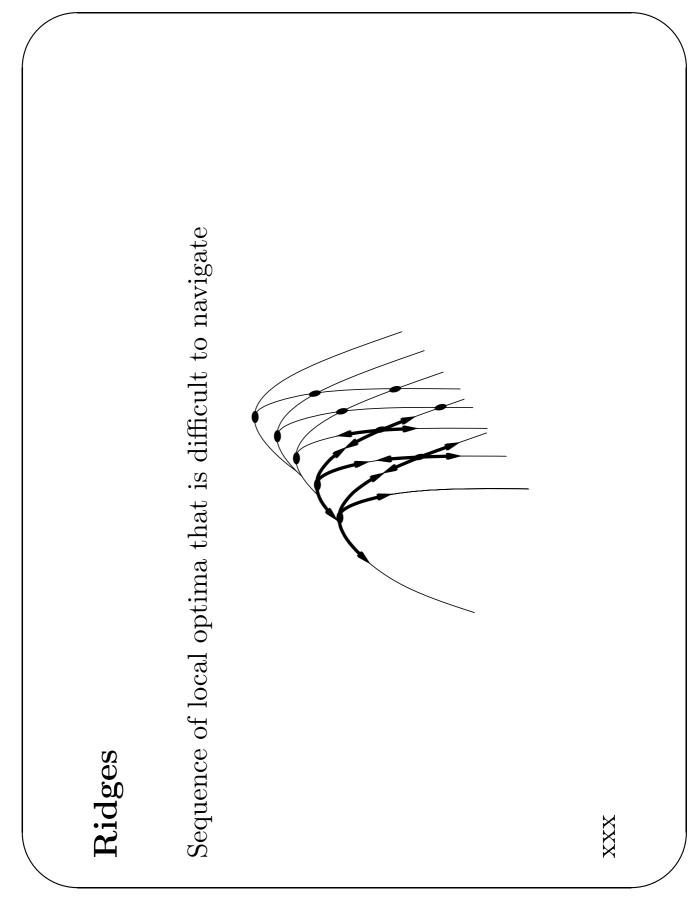
Ridge

#### Plateaux

Allow sideway moves



- For shoulder, good solution
- For flat local optima, may result in an infinite loop Limit number of moves



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Choose to disobey the heuristic, sometimes
Parameter: How often?

- First-choice hill climbing
   Choose first best neighbor examined
   Good solution when we have too many neighbors
- Random-restart hill climbing
  A series of hill-climbing searches from random initial states

- $\rightarrow$  Repeat random restart
  - for a fixed number of iterations, or
  - until best results have not been improved for a certain number of iterations

# Simulated annealing (I)

Basic idea: When stuck in a local maximum allow few steps towards less good neighbors to escape the local maximum

Start from any state at random, start count down and loop until time is over:

Pick up a neighbor at <u>random</u>

Set  $\Delta E = \text{value(neighbor)} - \text{value(current state)}$ 

If  $\Delta E > 0$  (neighbor is better)

then move to neighbor

else  $\Delta E < 0$  move to it with probability < 1

Transition probability  $\simeq e^{\Delta E/T} \begin{cases} \Delta \text{E is negative} \\ \text{T: count-down time} \end{cases}$  as time passes, less and less likely to make the move towards 'unattractive' neighbors

Analogy to physics:

Gradually cooling a liquid until it freezes

If temperature is lowered sufficiently slowly, material
will attain lowest-energy configuration (perfect order)

Count down  $\longleftrightarrow$  Temperature

Moves between states  $\longleftrightarrow$  Thermal noise

Global optimum  $\longleftrightarrow$  Lowest-energy configuration

#### Optimization problems

#### Decision problems

State value  $\longleftrightarrow$  Number of constraints violated

Sub-optimal state  $\longleftrightarrow$  Inconsistent state

Optimal state  $\longleftrightarrow$  Consistent state

### Local beam search

- $\bullet$  Keeps track of k states
- Mechanism:

Begins with k states

At each step, all successors of all k states generated Goal reached? Stop.

Otherwise, selects k best successors, and repeat.

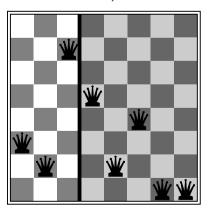
- Not exactly a k restarts: k runs are not independent
- <u>Stochastic</u> beam search increases diversity

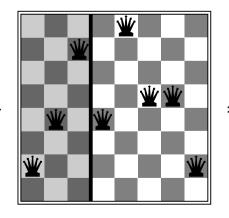
- Basic concept: combines two (parent) states
- Mechanism:

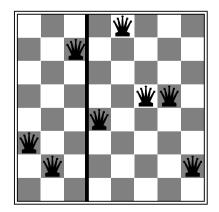
Starts with k random states (population)

Encodes individuals in a compact representation (e.g., a string in an alphabet)

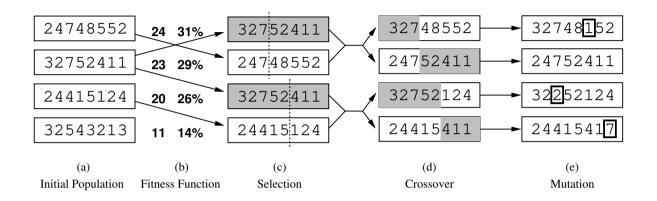
Combines partial solutions to generate new solutions (next generation)







# Important components of a genetic algorithm



- Fitness function ranks a state's quality, assigns probability for selection
- Selection randomly chooses pairs for combinations depending on fitness
- Crossover point randomly chosen for each individual, offsprings are generated
- Mutation randomly changes a state