Title: Local Search

Required reading: AIMA, Chapter 4

LWH: Chapters 6, 10, 13 and 14.

Introduction to Artificial Intelligence CSCE 476-876, Fall 2018

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Outline Iterative improvement search:

- Hill-climbing
- Simulated annealing
- ...

Types of Search (I)

- 1- Uninformed vs. informed
- 2- Systematic/constructive vs. iterative improvement

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Iterative improvement (a.k.a. local search)

— Sometimes, the 'path' to the goal is irrelevant only the state description (or its quality) is needed

Iterative improvement search

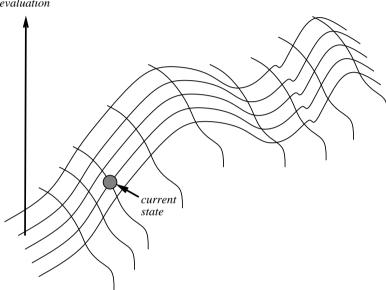
- choose a single current state, sub-optimal
- gradually modify current state
- generally visiting 'neighbors'
- until reaching a near-optimal state

Example: complete-state formulation of N-queens

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Main advantages of local search techniques

- 1. Memory (usually a constant amount)
- 2. Find reasonable solutions in large spaces where we cannot possibly search the space exhaustively
- 3. Useful for optimization problems: best state given an objective function (quality of the goal)



- All states are layed up on the surface of a landscape
- A state's location determines its neighbors (where it can move)
- A state's elevation represents its quality (value of objective function)
- Move from one neighbor of the current state to another state until reaching the highest peak

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Two major classes

- 1. Hill climbing (a.k.a. gradient ascent/descent)
 - \rightarrow try to make changes to improve quality of current state
- 2. Simulated Annealing (physics)
 - \rightarrow things can temporarily get worse

Others: tabu search, local beam search, genetic algorithms, etc.

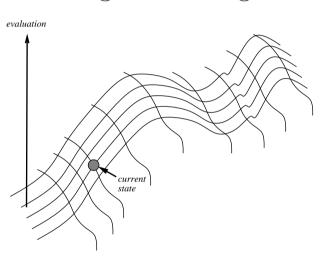
- → Optimality (soundness)? Completeness?
- \longrightarrow Complexity: space? time?
- → In practice, surprisingly good..

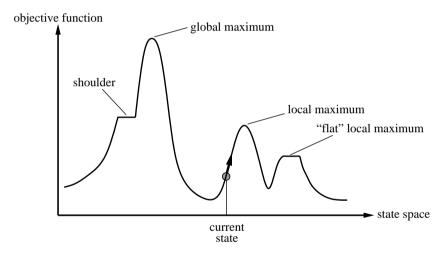
(eroding myth)

Start from any state at random and loop:

Examine all direct neighbors

If a neighbor has higher value then move to it else exit





Problems:

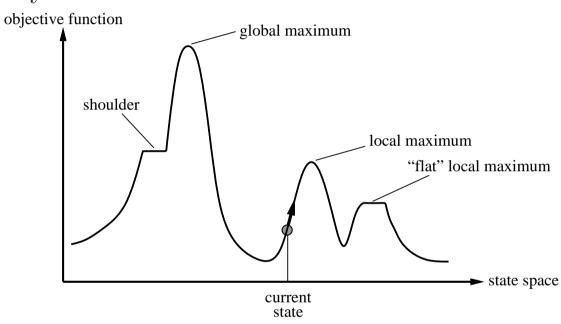
Local optima: (maxima or minima) search halts

Plateau: flat local optimum or shoulder

Ridge

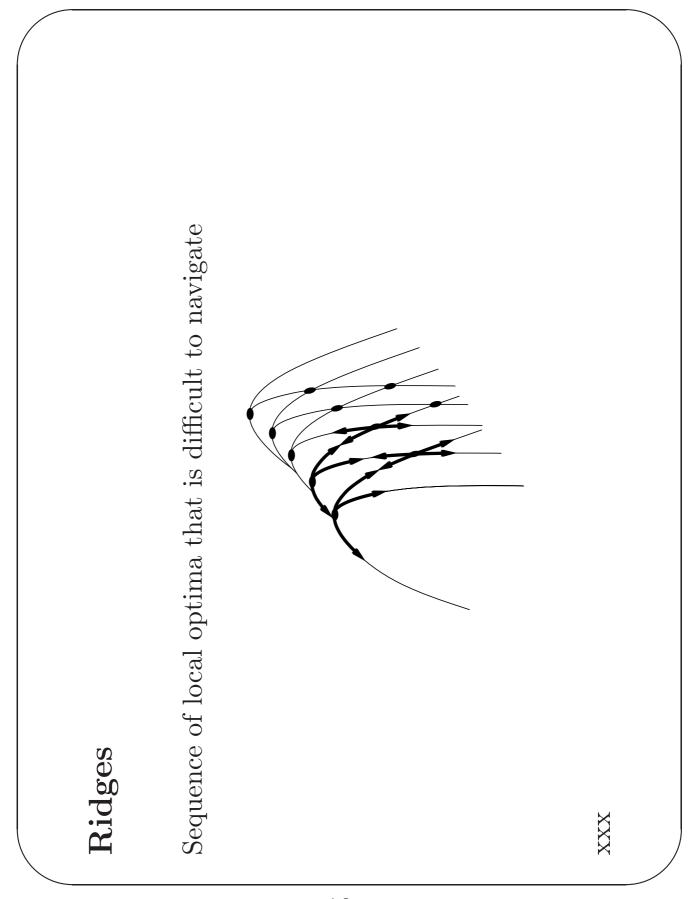
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Allow sideway moves



- For shoulder, good solution
- For flat local optima, may result in an infinite loop Limit number of moves

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• Stochastic hill climbing: random walk
Choose to disobey the heuristic, sometimes
Parameter: How often?

- First-choice hill climbing
 Choose first best neighbor examined
 Good solution when we have too many neighbors
- Random-restart hill climbing
 A series of hill-climbing searches from random initial states

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Random-restart hill-climbing

- → When HC halts or no progress is made
 re-start from a different (randomly chosen) starting
 save best results found so far
- \rightarrow Repeat random restart
 - for a fixed number of iterations, or
 - until best results have not been improved for a certain number of iterations

Simulated annealing (I)

Basic idea: When stuck in a local maximum allow few steps towards less good neighbors to escape the local maximum

Start from any state at random, start count down and loop until time is over:

Pick up a neighbor at <u>random</u>

Set ΔE = value(neighbor) - value(current state)

If $\Delta E > 0$ (neighbor is better)

then move to neighbor

else $\Delta E < 0$ move to it with probability < 1

Transition probability $\simeq e^{\Delta E/T} \begin{cases} \Delta \text{E is negative} \\ \text{T: count-down time} \end{cases}$ as time passes, less and less likely to make the move towards 'unattractive' neighbors

Simulated annealing (II)

Analogy to physics:

Gradually cooling a liquid until it freezes

If temperature is lowered sufficiently slowly, material
will attain lowest-energy configuration (perfect order)

Count down \longleftrightarrow Temperature

Moves between states \longleftrightarrow Thermal noise

Global optimum \longleftrightarrow Lowest-energy configuration

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Optimization problems

Decision problems

State value \longleftrightarrow Number of constraints violated

Sub-optimal state \longleftrightarrow Inconsistent state

Optimal state \longleftrightarrow Consistent state

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Local beam search

- \bullet Keeps track of k states
- Mechanism:

Begins with k states

At each step, all successors of all k states generated Goal reached? Stop.

Otherwise, selects k best successors, and repeat.

- \bullet Not exactly a k restarts: k runs are not independent
- <u>Stochastic</u> beam search increases diversity

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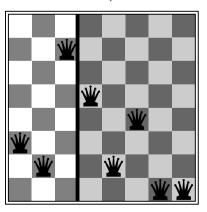
Genetic algorithms

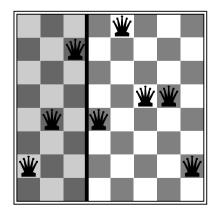
- Basic concept: combines two (parent) states
- Mechanism:

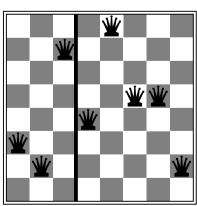
Starts with k random states (population)

Encodes individuals in a compact representation (e.g., a string in an alphabet)

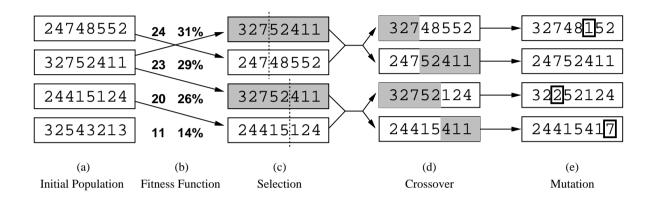
Combines partial solutions to generate new solutions (next generation)







Important components of a genetic algorithm



- Fitness function ranks a state's quality, assigns probability for selection
- Selection randomly chooses pairs for combinations depending on fitness
- Crossover point randomly chosen for each individual, offsprings are generated
- Mutation randomly changes a state